

Distributed Sensor Networks with Collective Computation (DSN-CC) for *In-Situ* Sensing

A. Mielke, C. Boyle, S. Brennan J. Karlin¹, A. Maccabe¹, B. Martinez, D. Torney
Los Alamos National Laboratory, Los Alamos, NM 87545, ¹University of New Mexico, Albuquerque, NM 87131
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Classical Sensor Network vs. DSN-CC Approach

Classical Advantages

- Little/no processing at the sensor.
- Simple sensor and network design.
- Raw data available at a central processing station (CPS).

DSN-CC Advantages

- Central processor absent.
- Tolerant to single-point failures.
- Easier scale-up in sensor number.

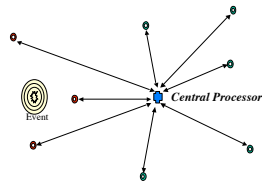


Figure 1: Classical Sensor Network Topology.

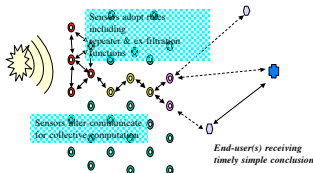


Figure 2: Distributed Sensor Network with Collective Computation Approach.

Theoretic Prediction of Energy and Time

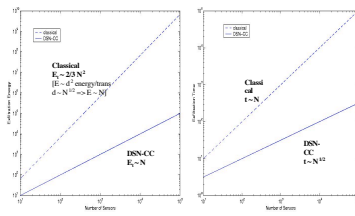


Figure 3: Energy and time for exfiltration scaling with sensor network size for Classical and DSN-CC approaches.

Commercial Wireless Sensor Mesh Networks

- Self-organizing/self-healing.
- Spread spectrum/ multi-hopping.
- Little processing power.

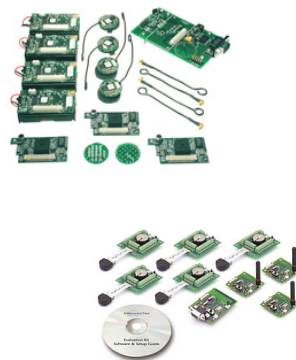


Figure 4: COTS Wireless Mesh Networks from Crossbow Technology, Millennial Net and Ember Corporation.

Source Detection Application

- Radioactive source detection.
- Heterogeneous network approach.
- Motes detect vehicle presence.
- PDA's record and evaluate information from radiation detectors.

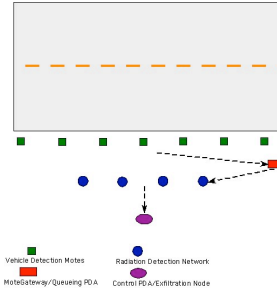


Figure 6: Source detection network design.



Figure 7: Deployed vehicle detection mote network.

Bayesian Radiation Detection Methods

- Use counts collected in the network in successive intervals and collected background statistics.
- Integrate over possible trajectories.
- Results indicate the probability a source is present.

$$\int_{h_m}^{h_u} \int_{v_m}^{v_u} \int_{x_m}^{x_u} \Pr(c_{11}, c_{12}, \dots, c_{\Phi\Phi} | a, h, v, x) dh dv dx$$

$$\int_{h_m}^{h_u} \int_{v_m}^{v_u} \int_{x_m}^{x_u} \Pr(c_{11}, c_{12}, \dots, c_{\Phi\Phi} | a, h, v, x) dh dv dx$$

- In simulation:
 - Background rate = 10 cnts/sec.
 - Sensors placed in a rectangle 10 m x 600 m.
 - Source velocities between 20 and 60 km/hr and constant.

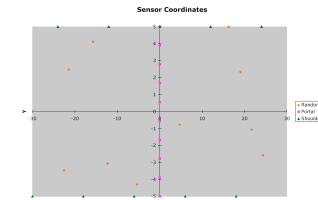


Figure 8: Sensor configurations modeled using Bayesian techniques.

Amplitude	False Negative Rate	False Positive Rate
1	0.5	0.48
10	0.42	0.28
100	0.17	0.04
1000	0.002	0.001

Table 1: Simulation detection results for a network of 10 sensors deployed in a random arrangement.

Amplitude	False Negative Rate	False Positive Rate
1	0.46	0.5
10	0.16	0.04
100	0.00	0.00
1000	*	*

Table 2: Simulation detection results for a network of 100 sensors deployed in a random arrangement.

Bayesian Estimation of Radioactive-Source Parameters

$$\langle a^i h^j v^k \rangle = \frac{\int_{h_m}^{h_u} \int_{v_m}^{v_u} \int_{x_m}^{x_u} a^i h^j v^k \Pr(c_{11}, c_{12}, \dots, c_{\Phi\Phi} | a, h, v) da dh dv}{\int_{h_m}^{h_u} \int_{v_m}^{v_u} \int_{x_m}^{x_u} \Pr(c_{11}, c_{12}, \dots, c_{\Phi\Phi} | a, h, v) da dh dv}$$

- Assume these are independent Poisson random variables.
- $\langle a \rangle$ = source amplitude
- $\langle h \rangle$ = height of the trajectory above the line of equally-spaced sensors
- $\langle v \rangle$ = source velocity
- The estimates are characterized by a mean and standard deviation plotted in the following figures.
- Details in Nemzek *et al.*, Distributed Sensor Networks for Detection of Mobile Radioactive Sources, *IEEE Transactions on Nuclear Science*, **51**, in press (2004).

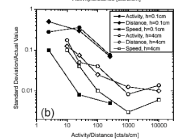
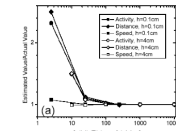


Fig. 9. Simulation results for a network of 10 sensors (a) and 100 sensors (b). The average first moments are plotted after five realizations of Poisson random variables with the same expectations: for each time interval and each sensor. (b). The standard deviations of the first moments over the five realizations are plotted, after normalizing by the parameter value, as in 5a.

Conclusions

- This work demonstrates the capabilities of distributed sensor networks for the detection of mobile radioactive sources.
- These networks employ heterogeneous wireless nodes and heterogeneous sensors.
- Simulation and modeling guide system development and implementations.
- Bayesian methods are practical for source detection, but further adaptation is required.